

# A Heuristic Algorithm for Student-Project Allocation Problem

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Abstract. The Student-Project Allocation problem with lecturer preferences over Students with Ties (SPA-ST) is to find a stable matching of students and projects to satisfy the constraints on student preferences over projects, lecturer preferences over students, and the maximum number of students given by each project and lecturer. This problem has attracted many researchers because of its wide applications in allocating students to projects at many universities worldwide. However, the main weakness of existing algorithms is their high computational cost. In this paper, we propose a heuristic algorithm to improve solution quality and execution time for solving the SPA-ST problem of large sizes. Experimental results on randomly generated datasets show that our algorithm outperforms the state-of-the-art algorithm regarding solution quality and execution time.

**Keywords:** Student-Project Allocation Problem  $\cdot$  Heuristic algorithm  $\cdot$  Blocking pairs  $\cdot$  Stable matching  $\cdot$  MAX-SPA-ST  $\cdot$  Large sizes

## 1 Introduction

The problem of allocating students to projects based on their preferences, called SPA [2,7,18,19,21], is to find a stable matching of the students and the projects to satisfy the constraints on their preference lists. This problem has played an important role at many universities in the world [6,10,14,17]. However, it has a strict constraint on preference lists: students and lecturers must rank given projects in a certain order that cannot cover a reality case: two projects are ranked in the same order of preference in their lists. Abraham et al. [1] proposed a new variant of the SPA problem, called preferences over Students containing Ties (SPA-ST), with an adjustment that helps students have more options

when choosing projects from the lecturers: the list of preferences of lecturers and students can contain equality relations.

In the SPA-ST problem, there are three stability criteria of matching: weakly stable, strongly stable, or super-stable matching [19,20]. Irving et al. [22] proved that a super-stable matching is strongly stable, and a strongly stable matching is a weakly stable matching. If a super-stable matching is found, all weakly stable matching always exist and have different sizes [11]. Therefore, the problem of finding a maximum size weakly stable or super-stable matchings, whose goal is to find a stable matching with a maximum number of matched students, may not exist because the constraints are too tight [15,20,22].

Practically, the problem of finding a maximum weakly stable matching is the most suitable for real-life applications because it focuses on assigning as many students as possible to projects. This problem is known as the MAX-SPA-ST problem and it has attracted much attention from the research community because of its application in education optimization problems. Some universities applied the MAX-SPA-ST problem to optimize the assignment of projects for lecturers to satisfy the constraints of large-scale problems, such as the School of Computer Science, the University of Glasgow [14], Faculty of Science, University of Southern Denmark [6], Department of Computer Science, York University, and elsewhere [3-5,8]. Unfortunately, finding an efficient algorithm to solve the MAX-SPA-ST of large sizes is still a main challenge for the research community. The approximation algorithm is one of the popular methods for solving the SPA-ST problem [1,12,16,21]. Cooper et al. [7] first proposed a 3/2approximation algorithm named APX for solving the MAX-SPA-ST based on Király's idea [13]. Latter, Manlove et al. [15] presented an Integer Programming (IP) model to find a strongly stable matching for SPA-ST. Recently, Olaosebikan et al. [19] provided a polynomial-time algorithm to find a super-stable matching. However, they proved that it might not exist for the SPA-ST problem.

In this paper, we call a *weakly stable* matching a *stable* matching. Accordingly, we propose a new heuristic algorithm for solving the MAX-SPA-ST problem. The main difference between our algorithm from the others is that we design *two heuristic functions* to estimate reasonable solutions: the first is used to choose the best project to match with students, while the second is to discard the worst student from the matching when the project or lecturer is *over-subscribed*. By combining two functions, our algorithm can find a suitable solution within a reasonable time. Experimental results show that our proposed algorithm performs better in terms of the average execution time and percentage of perfect matchings compared to the most recent APX algorithm [7] for solving the MAX-SPA-ST problem of large sizes.

The rest of this paper is organized as follows. Section 2 presents preliminaries of the SPA-ST problem, Sect. 3 describes our proposed algorithm, Sect. 4 discusses our experimental results, and Sect. 5 concludes our work.

### 2 Preliminaries

An SPA-ST instance consists of a set  $S = \{s_1, s_2, \dots, s_n\}$  of students, a set  $\mathcal{P} = \{p_1, p_2, \dots, p_q\}$  projects, and a set  $\mathcal{L} = \{l_1, l_2, \dots, l_m\}$  of lecturers. Each student  $s_i$  ranks a set of acceptable projects in order of preference containing ties. Each lecturer  $l_k \in \mathcal{L}$  offers a set of projects and ranks a set of students in a preference list containing ties. Each lecturer has a capacity  $d_k \in \mathbb{Z}^+$  indicating the maximum number of students assigned to  $l_k$ . Each project  $p_j \in \mathcal{P}$  is offered by one lecturer and has a capacity  $c_j \in \mathbb{Z}^+$  indicating the maximum number of students assigned to it. For example, an SPA-ST instance given in Table 1 consists of a set of  $S = \{s_1, s_2, s_3, s_4, s_5, s_6, s_7\}$  of students, a set  $\mathcal{P} = \{p_1, p_2, p_3, p_4, p_5, p_6, p_7, p_8\}$  of projects, and a set  $\mathcal{L} = \{l_1, l_2, l_3\}$  of lecturers.

Students' preferences	Lecturers' preferences	
$s_1: (p_1 \ p_7)$	$l_1$ : $(s_7 \ s_4) \ s_1 \ s_3 \ (s_2 \ s_5) \ s_6$	$l_1$ offers $p_1, p_2, p_3$
$s_2: p_1 \ p_3 \ p_5$	$l_2: s_3 \ s_2 \ s_7 \ s_5$	$l_2$ offers $p_4, p_5, p_6$
$s_3$ : $(p_2 \ p_1) \ p_4$	$l_3$ : $(s_1 \ s_7) \ s_6$	$l_3$ offers $p_7, p_8$
$s_4$ : $p_2$		
$s_5$ : $p_1 p_4$		
$s_6: p_2 \ p_8$	Project capacities	$c_1 = 2, c_j = 1, (2 \le j \le 8)$
$s_7$ : $(p_5 \ p_3) \ p_8$	Lecturer capacities	$d_1 = 3, d_2 = 2, d_3 = 2$

 Table 1. An example of SPA-ST instance

For any pair  $(s_i, p_j) \in S \times P$ , where  $p_j$  is offered by  $l_k$ , we refer  $(s_i, p_j)$  as an *acceptable pair* if  $s_i$  and  $p_j$  both find each other acceptable, i.e.,  $p_j$  is ranked by a student  $s_i$  and a lecturer  $l_k$  ranks  $s_i$ . Each student  $s_i \in S$  has a set  $A_i \subseteq P$ of acceptable projects that they rank in the order of preference. We let  $R_{s_i}(p_j)$ and  $R_{l_k}(s_i)$  be the rank of  $p_i$  in  $s_i$ 's ranks list and the rank of  $s_i$  in  $l_k$ 's ranks list, respectively.

A matching  $\mathcal{T}$  of an SPA-ST instance is a set of acceptable pairs  $(s_i, p_j)$ or  $(s_i, \emptyset)$  such that  $|\mathcal{T}(s_i)| \leq 1$  for all  $s_i \in S$ ,  $|\mathcal{T}(p_j)| \leq c_j$  for all  $p_j \in \mathcal{P}$ , and  $|\mathcal{T}(l_k)| \leq d_k$  for all  $l_k \in \mathcal{L}$ , meaning that each  $s_i$  belongs to at most one pair. A project  $p_j$  is under-subscribed, full, or over-subscribed if  $|\mathcal{T}(p_j)| < c_j$ ,  $|\mathcal{T}(p_j)| = c_j$ , or  $|\mathcal{T}(p_j)| > c_j$ , respectively. Similarly, a lecturer  $l_k$  is undersubscribed, full, or over-subscribed if  $|\mathcal{T}(l_k)| < d_k$ ,  $|\mathcal{T}(l_k)| = d_k$ , or  $|\mathcal{T}(l_k)| > d_k$ , respectively. If an acceptable project and lecturer are under-subscribed, this project is a potential project. If  $(s_i, p_j) \in \mathcal{T}$ , then  $s_i$  is matched to  $p_j$ , denoted by  $\mathcal{T}(s_i) = p_j$ . If  $\mathcal{T}(s_i) = \emptyset$ , then  $s_i$  is unassigned in  $\mathcal{T}$ , and we let the set of unsigned students be  $\mathcal{U}$ .

Given a matching  $\mathcal{T}$ , a pair  $(s_i, p_j) \in \mathcal{S} \times \mathcal{P}$  is a blocking pair in  $\mathcal{T}$  if it meets the conditions of (1), (2), and (3) as follows:

- 1.  $s_i$  and  $p_j$  find accept each other;
- 2.  $s_i$  prefers  $p_j$  to  $\mathcal{T}(s_i)$  or  $\mathcal{T}(s_i) = \emptyset$ ;

- 3. either (a), (b) or (c) holds as follows:
  - (a)  $|\mathcal{T}(p_j)| < c_j$  and  $|\mathcal{T}(l_k)| < d_k$ ;
  - (b)  $|\mathcal{T}(p_j)| < c_j, |\mathcal{T}(l_k)| = d_k$ , and (i) either  $s_i \in \mathcal{T}(l_k)$  or (ii)  $l_k$  prefers  $s_i$  to the worst student in  $\mathcal{T}(l_k)$ ;
  - (c)  $|\mathcal{T}(p_j)| = c_j$  and  $l_k$  prefers  $s_i$  to the worst student in  $\mathcal{T}(p_j)$ .

A matching  $\mathcal{T}$  is *stable* if it admits no blocking pair. Otherwise, it is *unstable*. The size of a stable matching  $\mathcal{T}$ , denoted by  $|\mathcal{T}|$ , is the number of students assigned in  $\mathcal{T}$ . If  $|\mathcal{T}| = n$ , then  $\mathcal{T}$  is a *perfect* matching. Otherwise,  $\mathcal{T}$  is a *non-perfect* matching.  $|\mathcal{U}|$  is the number of unassigned students in a *non-perfect* matching  $\mathcal{T}$ . If the size of a weakly stable matching is equal to n, denoted by  $|\mathcal{T}| = n$ , then  $\mathcal{T}$  is a *perfect* matching. Otherwise,  $\mathcal{T}$  is *non-perfect*.

### 3 Proposed Algorithm

In this section, we introduce our proposed algorithm. The core of our algorithm is two *heuristic functions* that can improve execution time and solution quality for the MAX-SPA-ST problem. The first one helps students to choose a suitable project for matching, while the second one determines which students will be removed from the current matching when the lecturer or project is *oversubscribed*.

#### 3.1 Heuristic Functions

This section presents two heuristic functions to guide students and lecturers to select appropriate projects and students, respectively, so that our algorithm can reach a perfect matching with a better solution quality and shorter execution time. To do so, we design two heuristic functions as follows:

(1) The heuristic function  $h(p_j)$ : For each student  $s_i \in S$ , we define the first heuristic function  $h(p_j)$  for every project  $p_j$  in  $s_i$ 's rank list, where  $p_j$  is offered by  $l_k$ , to choose the best project in terms of the minimum value of  $h(p_j)$  in Eq. 1 as follows:

$$h(p_j) = R_{s_i}(p_j) - \min(d_k - |\mathcal{T}(l_k)|, 1)/2 - (c_j - |\mathcal{T}(p_j)|)/(2 \times c_j + 1).$$
(1)

If  $(s_i, p_j)$  is an acceptable pair, then  $1 \leq R_{s_i}(p_j) \leq q$ . If  $l_k$  is full, i.e.,  $d_k - |\mathcal{T}(l_k)| = 0$ , then  $min(d_k - |\mathcal{T}(l_k)|, 1)/2 = 0$ . If  $l_k$  is under-subscribed, i.e.,  $|\mathcal{T}(l_k)| < d_k$ , then  $min(d_k - |\mathcal{T}(l_k)|, 1)/2 = 0.5$  for all  $l_k \in \mathcal{L}$ . Besides, we have  $0 \leq c_j - |\mathcal{T}(p_j)| \leq c_j$ , then  $0 \leq (c_j - |\mathcal{T}(p_j)|)/(2 \times c_j + 1) < 0.5$  for all  $p_j \in \mathcal{P}$ , meaning that  $0 < h(p_j) \leq q$ .

(2) The heuristic function  $g(s_t)$ : For each student  $s_i \in S$ , when  $s_i$  offers to  $p_j$ , if  $p_j$  is full or  $l_k$  is full, then we choose the worst student in terms of the maximum heuristic value to remove her/his from the current matching. To do this, we define a heuristic function  $g(s_t)$  in Eq. 2 as follows:

$$g(s_t) = R_{l_k}(s_t) + t(s_t) + r(s_t)/(q+1).$$
(2)

For each student  $s_t \in \mathcal{T}(l_k)$ , we have  $1 \leq R_{l_k}(s_t) \leq n$ . Moreover,  $t(s_t) = sum(min(d_z - |\mathcal{T}(l_z)|, 1) \times min(c_u - |\mathcal{T}(p_u)|, 1) \times n)$ , where  $p_u$  is the same ties with  $\mathcal{T}(s_t)$  in  $s_t$ 's rank list and  $p_u$  is offered by  $l_z$ . If  $p_u$  is under-subscribed, i.e.,  $|\mathcal{T}(p_u)| < c_u$ , then  $1 \leq c_u - |\mathcal{T}(p_u)| \leq c_u$ , thus we have  $min(c_u - |\mathcal{T}(p_u)|, 1) = 1$ . Otherwise, if  $p_u$  is full, i.e.,  $|\mathcal{T}(p_u)| = c_u$ , then  $c_u - |\mathcal{T}(p_u)| = 0$ , thus we have  $min(c_u - |\mathcal{T}(p_u)|, 1) = 1$  or 0, if  $l_z$  is under-subscribed or full, respectively. If  $p_u$  is a potential project, then we have  $min(d_z - |\mathcal{T}(l_z)|, 1) \times min(c_u - |\mathcal{T}(p_u)|, 1) \times n = n$ , otherwise,  $min(d_z - |\mathcal{T}(l_z)|, 1) \times min(c_u - |\mathcal{T}(p_u)|, 1) \times n = 0$ . Thus, we have  $0 \leq t(s_t) \leq (q-1) \times n$ . Let  $r(s_t)$  be the number projects ranked by  $s_t$ , we have  $1 \leq r(s_t) \leq q$ , thus  $s_t \in \mathcal{T}(l_k)$ .

### 3.2 Our Algorithm

This section presents our proposed algorithm, called HAG (Algorithm 1). At the beginning, HAG assigns a matching  $\mathcal{T} = \emptyset$  and a count variable  $v(s_i) = 0$  for all students  $s_i \in \mathcal{S}$ . At each iteration, if there exists an unassigned  $s_i \in \mathcal{S}$  such that  $s_i$ 's rank list is non-empty, then HAG runs as follows. First, it calculates the heuristic function  $h(p_j)$  for each project  $p_j \in \mathcal{P}$  in  $s_i$ 's rank list. Then,  $s_i$  proposes a project  $p_j$  corresponding to the minimum value of  $h(p_j)$ . Let  $l_k$  be a lecturer who offers  $p_j$ , we consider the following cases:

- 1. If both  $p_j$  and  $l_k$  are under-subscribed, HAG adds  $(s_i, p_j)$  into  $\mathcal{T}$ .
- 2. If  $p_j$  is full, HAG calculates  $g(s_t)$  for all  $s_t \in \mathcal{T}(p_j)$  and chooses a student  $s_t$  with maximal value of  $g(s_t)$  by the function Choose\_Student( $\mathcal{T}(p_j), l_k$ ). If  $g(s_t) > n + 1$  or  $R_{l_k}(s_t) > R_{l_k}(s_i)$ , then HAG removes  $(s_t, p_j)$ , adds  $(s_i, p_j)$  into  $\mathcal{T}$  and deletes  $p_j$  in  $s_t$ 's rank list if  $g(s_t) < n+1$ . Otherwise, HAG deletes  $p_j$  in  $s_i$ 's rank list. Note that if  $g(s_t) > n + 1$ , then  $s_t$  contains a potential project with the same ties as  $p_j$  in  $s_t$ 's rank list.
- 3. If  $l_k$  is full, HAG calculates  $g(s_w)$  for all  $s_w \in \mathcal{T}(l_k)$  and chooses a student  $s_w$  with maximal value of  $g(s_w)$  by the function  $Choose\_Student(\mathcal{T}(l_k), l_k)$ . If  $g(s_w) > n + 1$  or  $R_{l_k}(s_w) > R_{l_k}(s_i)$ , then HAG removes  $(s_w, p_u)$ , where  $p_u = \mathcal{T}(s_w)$ , and adds  $(s_i, p_j)$  into  $\mathcal{T}$ . If  $g(s_w) < n + 1$ , then HAG deletes  $p_u$  in  $s_w$ 's rank list. Otherwise, it deletes  $p_j$  in  $s_i$ 's rank list. When a project  $p_u$  is removed, it can form blocking pairs with students in  $\mathcal{T}(l_k)$ , then HAG calls the function  $Repair(p_u, l_k)$  to break blocking pairs satisfying the condition of (3bi).

The above process repeats until a stable matching  $\mathcal{T}$  is found. If  $|\mathcal{T}| = n$ , then HAG returns a perfect matching. Otherwise, HAG calls the function  $Escape(p_u, l_k)$  to assign *unassigned* students for the current stable matching. Our HAG stops when a *perfect* matching is found or all *unassigned* students cannot find any projects to assign them. In the latter case, the algorithm returns a stable matching of a maximum size found so far.

```
Algorithm 1: HAG algorithm for MAX-SPA-ST
```

```
Input: An SPA-ST instance I
     Output: A stable matching \mathcal{T}
 1. function HAG(I)
 2.
           \mathcal{T} := \emptyset:
           v(s_i) := 0, \forall s_i \in \mathcal{S};
 3.
           while true do
 4.
                s_i := an unassigned student that s_i's rank list is non-empty;
 5.
 6.
                if there exists no student s_i then
                     if |\mathcal{T}| = n then break;
 7.
                     else
 8.
                           \mathcal{T}' := \operatorname{Escape}(\mathcal{T});
 9.
                          if \mathcal{T}' = \mathcal{T} then break;
10.
                          \mathcal{T} := \mathcal{T}';
11.
                          continue:
12.
13
                     end
                end
14.
15.
                for each p_i \in A_i do
                     l_k := a lecturer who offers p_i;
16.
                     h(p_j) := R_{s_i}(p_j) - min(d_k - |\mathcal{T}(l_k)|, 1)/2 - (c_j - |\mathcal{T}(p_j)|) / (2 \times c_j + 1);
17.
                end
18.
                p_j := \operatorname{argmin}(h(p_j) > 0), \forall p_j \in \mathcal{P};
19.
                l_k := a lecturer who offers p_i;
20.
                if p_i and l_k are under-subscribed then
21.
22.
                     \mathcal{T} := \mathcal{T} \cup \{(s_i, p_j)\};
23.
                else if p_i is full then
                     [s_t, g(s_t)] := Choose_Student(\mathcal{T}(p_j), l_k);
24.
                     if g(s_t) > n+1 or R_{l_k}(s_i) < R_{l_k}(s_t) then
25.
                           \mathcal{T} := \mathcal{T} \setminus \{(s_t, p_i)\} \cup \{(s_i, p_i)\};
26.
                          if g(s_t) < n+1 then
27.
                               R_{s_t}(p_j) := 0;
28.
29.
                           end
                     else
30
31.
                          R_{s_i}(p_j) := 0;
                     end
32.
33.
                else
                     [s_w, g(s_w)] := Choose_Student(\mathcal{T}(l_k), l_k);
34.
                     if g(s_w) > n+1 or R_{l_k}(s_i) < R_{l_k}(s_w) then
35.
                           \mathcal{T} := \mathcal{T} \setminus \{(s_w, p_u)\} \cup \{(s_i, p_j)\}, \text{ where } p_u = \mathcal{T}(s_w);
36.
                          Repair (p_u, l_k);
37.
                          if g(s_w) < n+1 then
38.
39.
                                R_{s_w}(p_u) := 0;
                          end
40.
41.
                     else
                          R_{s_i}(p_j) := 0;
42.
                     end
43.
44.
                end
45.
           end
46.
           return \mathcal{T};
47. end function
```

The function  $Choose\_Student(\mathcal{T}(p_j), l_k)$  is used to choose a student with the maximum value of  $g(s_t)$ . Let X be the set of students such that  $X = \mathcal{T}(p_j)$ , where  $p_j$  is full, or  $X = \mathcal{T}(l_k)$  where  $l_k$  is full. For each  $s_t \in X$ , the algorithm calculates the heuristic value of  $g(s_t)$  and returns a student  $s_t$  with the maximum value of  $g(s_t)$ .

The function  $Repair(p_u, l_k)$  is used to break blocking pairs satisfying the condition of (3bi). When a project  $p_u$  is removed, for each  $s_k \in \mathcal{T}(l_k)$ , if  $R_{s_k}(p_u) < R_{s_k}(p_z)$ , where  $p_z = \mathcal{T}(s_k)$ , then the algorithm removes  $(s_k, p_z)$  and adds  $(s_k, p_u)$  into  $\mathcal{T}$ . This process repeats for each project which is removed until it cannot form blocking pairs.

If HAG reaches a *stable* matching but it is *non-perfect* matching, it gets stuck at a local minimum. At each iteration, for each student  $s_i \in \mathcal{S}$ , HAG proposes a project  $p_i \in \mathcal{P}$  which is the minimum rank in  $s_i$ 's rank list and adds  $(s_i, p_j)$ into matching  $\mathcal{T}$ . Since ties were given in  $l_k$ 's rank list  $(p_i \text{ is offered by } l_k)$ , there exists a different student  $s_u$  who prefers the most project  $p_i$  or  $p_z$  ( $p_z$  is offered by  $l_k$ ) where  $R_{l_k}(s_u) = R_{l_k}(s_i)$ . When  $s_u$  applies to  $p_j$  ( $p_j$  is full) or  $p_z$  ( $l_k$  is full), we keep  $(s_i, p_j)$  and reject  $(s_u, p_z)$  or  $(s_u, p_j)$ , then HAG can result in a non-perfect matching. If we add  $(s_u, p_z)$  or  $(s_u, p_j)$  and remove  $(s_i, p_j)$ , HAG can result in a *perfect* matching. This means that we can add  $(s_u, p_z)$  or  $(s_u, p_i)$ and remove  $(s_i, p_i)$ , then  $s_i$  applies to other projects. Moreover, we can improve stable matchings' size by using the function  $Escape(\mathcal{T})$ . For each unassigned student  $s_u \in \mathcal{S}$ , the algorithm finds a project  $p_z$  such that there exists a student  $s_i$  where  $p_j$  is assigned to  $s_i$  and  $v(s_u) \geq v(s_i)$ . Then, the algorithm replaces  $(s_i, p_j)$  by  $(s_u, p_z)$  in  $\mathcal{T}$  and increases the value of  $v(s_u)$ . When  $p_j$  is removed, it can form blocking pairs with other students in  $\mathcal{T}(l_k)$ , thus we call the function  $Repair(p_i, l_k)$  to break blocking pairs. It should be noted that the condition  $v(s_u) \geq v(s_i)$  means that the number of replacements of  $s_u$  is higher than that of  $s_i$ , i.e.,  $s_u$  is prioritized to assign to  $p_z \in l_k$ . Accordingly, matching  $\mathcal{T}$  is unstable and  $s_i$  is an unassigned student, then  $s_i$  proposes other projects in  $s_i$ 's rank list.

### 4 Performance Evaluation

In this section, we present several experiments to evaluate the efficiency of our HAG algorithm. We compared the average execution time and solution quality found by HAG with those found by the approximation algorithm, named APX [7] for solving MAX-SPA-ST problem of large sizes. We implemented these algorithms by Matlab R2019a software on a system with Xeon-R Gold 6130 CPU 2.1 GHz computer with 16 GB RAM.

**Datasets**: To perform experiments, we adapted a random SMTI problem generator [9] to generate SPA-ST instances with seven parameters  $(n, m, q, p_1, p_2, C, D)$ , where n is the number of students, m is the number of lecturers, q is the number of projects,  $p_1$  is the probability of incompleteness,  $p_2$  is the probability of ties, C is the total capacity of projects, denoted by  $C = \sum_{j=1}^{q} c_j$  where  $c_j$  is the capacity of project  $p_j$  offered by lecturer  $l_k$ , D is the total capacity of lecturers, denoted by  $D = \sum_{k=1}^{m} d_k$  where  $d_k$  is the capacity of each lecturer  $l_k$ .

#### 4.1 Evaluate the Variation of Ties and Incompleteness

In this experiment, we evaluate the influence of the probability of  $p_1$  and  $p_2$ on the solution quality and execution time of HAG in comparison with APX. We generated SPA-ST instances by letting parameters  $(n, m, q, p_1, p_2, C, D)$ , in which  $n \in \{100, 200\}$ , m = 0.05n, q = 0.1n,  $p_1 \in [0.1, 0.8]$  and  $p_2 \in [0.0, 1.0]$ with step of 0.1. The total capacities of projects and lecturers are C = 1.2n, and D = 1.1n, respectively. In addition,  $c_j$  is distributed for each project  $p_j \in \mathcal{P}$ such that  $0.6C/q \leq c_j \leq 1.4C/q$  and  $d_k$  is set of each lecturer  $l_k \in \mathcal{L}$  such that  $d_k = D/m$ .

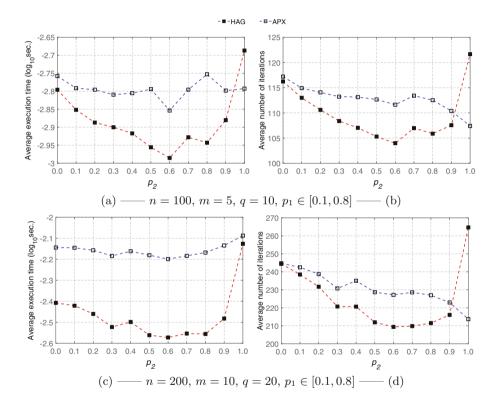


Fig. 1. Average execution time and average number of iterations of HAG vs. APX

We first compare the average execution time and the average number of iterations of HAG with APX for finding perfect matchings for n = 100 and n = 200. Then, we average results based on values of  $p_1$  which is shown in Fig. 1. Accordingly, we see that Figs. 1(a) and 1(c) show that HAG runs faster than APX for n = 100 and n = 200 with every value of  $p_2$ . When  $p_2$  increases from 0.0 to 0.9 for n = 100, HAG takes from  $10^{-2.98}(s)$  to  $10^{-2.68}(s)$ , while APX takes from  $10^{-2.85}(s)$  to  $10^{-2.75}(s)$ , but when  $p_2 = 1.0$ , the average execution

time of HAG increases. When n = 200, the average execution time of HAG increases from about  $10^{-2.58}(s)$  to  $10^{-2.28}(s)$ , while APX takes from  $10^{-2.23}(s)$  to  $10^{-2.16}(s)$ . Figures 1(b) and 1(d) give the average number of iterations used by HAG and APX for n = 100 and n = 200 with every  $p_2$ . HAG needs fewer iterations than APX for  $p_2$  from 0.0 to 0.9 for n = 100 and n = 200. This explains that HAG runs much faster than APX as shown in Figs. 1(a) and 1(c).

Next, we compare the percentage of perfect matchings and average number of unassigned students found by HAG and APX for every value of  $p_1$  and  $p_2$ . Our experimental results show that when  $p_1$  varies from 0.1 to 0.5 with step 0.1, both HAG and APX result in perfect matchings approximately, therefore we only show the results in Fig. 2 for values of  $p_1$  from 0.6 to 0.8 and every value of  $p_2$ .

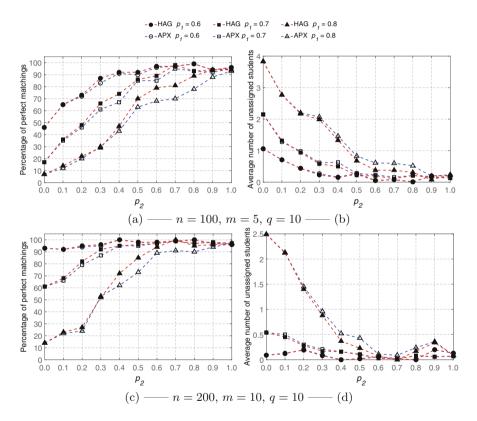


Fig. 2. Percentage of perfect matchings and number of unassigned students of HAG vs. APX

Figure 2 shows that when  $p_1$  increases to 0.8, it is difficult for finding perfect matchings, but HAG finds better the percentage of perfect matchings than that found by APX. When  $p_2$  varies from 0.1 to 1.0, HAG finds a much higher percentage of perfect matchings than APX as shown in Figs. 2(a) and 2(c).

Figures 2(b) and 2(d) show the average number of unassigned students found by HAG and APX. When  $p_2$  varies from 0.1 to 1.0, HAG obtains a much smaller number of unassigned students than APX in non-perfect matchings. This means that HAG finds better maximum stable matchings than APX when  $p_1$  increases in this experiment.

#### 4.2 Evaluate the Variation of the Problem of Large Sizes

In this experiment, we set  $n \in [1000, 10000]$  with step 1000,  $m \in [0.02n, 0.04n]$  step 0.01, q = 0.1n,  $p_1 = 0.9$ , and  $p_2 = 0.5$ . The total capacity of projects and lecturers is set in two cases as follows:

Case 1: C = 1.4n and  $0.7C \le D \le 0.9C$ , i.e., the capacity  $c_j$  of each project  $p_j$  is bound by  $0.6C/q \le c_j \le 1.4C/q$  and the capacity  $d_k$  of each lecturer  $l_k$  is bound by  $0.7\sum_{k=1}^{|P_k|} c_j \le d_k \le 0.9\sum_{k=1}^{|P_k|} c_j$ , where  $P_k$  is a set of projects  $p_j$  offered by lecturer  $l_k$ .

Case 2: C = 1.5n, and D = 1.2n, i.e., we distribute C to the capacity  $c_j$  of each project  $p_j$  such that  $0.6C/q \le c_j \le 1.4C/q$ . Next, we set the capacity of each lecturer  $l_k$  to be  $d_k = D/m$ .

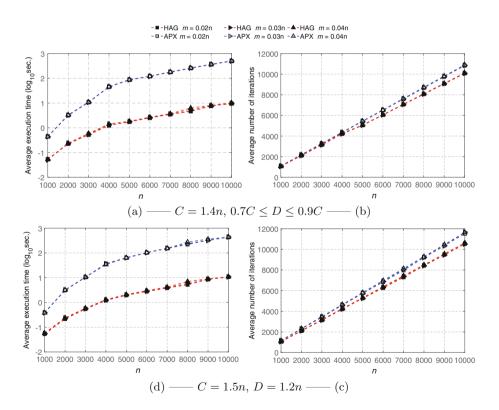


Fig. 3. Average execution time and average number of iterations HAG vs. APX

When  $p_1 = 0.9, 90\%$  of projects or students do not rank in students' rank lists or lecturers' rank lists, respectively. However, because the number of projects and students is larger, both HAG and APX can find approximately 100% of perfect matchings. Figure 3 shows that HAG runs faster from 10 to 80 times and needs fewer iterations than APX in two cases of capacities.

# 5 Conclusions

This paper proposed an efficient heuristic algorithm HAG to solve the large size MAX-SPA-ST problem. Our algorithm starts from an empty matching and finds a solution for the problem based on two proposed *heuristic functions* to improve the performance of the searching process. If the algorithm reaches a *non-perfect* matching, we propose a heuristics strategy to increase the size of the stable matching by suggesting *unassigned* students to projects in the same ties with its partner in the current matching. Our experimental results show that our algorithm overcomes the APX algorithm [7] in terms of execution time and solution quality for the MAX-SPA-ST of large sizes. In the future, we will extend this proposed approach to find *strongly stable* or *super-stable* matchings for the SPA-ST problem [20].

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